

The world's Best  
**A High Performance**

PID Control Algorithms

**TemcoLine™**  
DIGITAL PID CONTROLLER

T50 SERIES  
T30 SERIES  
N50 SERIES



PID Control Algorithms



## A High-performanced PID control algorithms

Super 2 degree of freedom PID Controllers

Temcoline's products are aimed at elevating the level of the industrial PID controller one step higher with our own high-precision electronics and control technology accumulated through development of sensors, industrial robots, flight vehicles and radars, etc. Our products are already being used in many companies and have earned positive response compare to other products from Japan and Europe. Join in advancing into the global market with industrial PID controller.



T50 SERIES



T30 SERIES

## The world's first Auto-sampling Time(50~250ms) Control

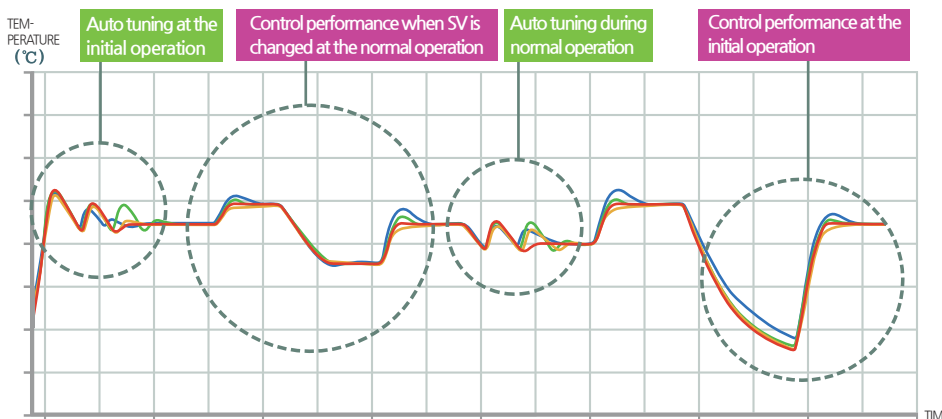
Auto-Sampling Time Control

The fast sampling is not good enough for optimal control because most of an actual temperature changes is moving slowly. Temcoline combined Auto-sampling time control technology into the existing PID control algorithms successfully and this provides an optimal control on an actual temperature changes under no conditions.



N50 SERIES

## Digital PID Controller Function Test



■ You could be checking this compared data in website.

## TemcoLine's products are...



SUPER 2 DEGREE OF FREEDOM

### Excellent control characteristics incomparable to other products

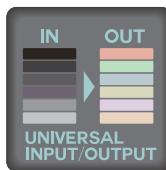
Super 2 degree of freedom PID algorithm allows to provide a fast response characteristic and high control stability while minimizing overshoot and undershoot during power-up or external load disturbance.



DIGITAL FILTERING

### TemcoLine's unique digital filtering technology

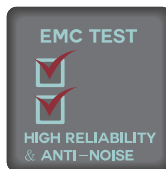
By implementing the intelligent digital filtering technology used for aircraft and robots, etc., all the products offer very stable control, especially in harsh work force.



UNIVERSAL INPUT/OUTPUT

### Universal input and output

The universal input and output design allows the user to simplify the initial setup for a new system.



HIGH RELIABILITY & ANTI-NOISE

### High reliability and anti-noise (EMC)

The series are to be delivered to market after a successful test for international standard EMC and 37 kinds of reliability in harsh conditions.

## Fully automated Test / Calibration system

Test and calibration processing in PID controller including other instrument & control products is most important factor to determine the product quality. All of our products pass through the several inspection procedures for quality assurance.

PCB inspection, Electrical test, Aging, Calibration and Final inspection are fully automated. This will provide guaranteed quality and minimize the workmanship error in the course of production.

Aging is processed for about 2 hours before calibration and tests. After the final test, the products go through load tests before being packed to make sure only perfect products with no quality problems are released.

### Fully automated Test / Calibration system



Automated Database System



Fully Automated Test/Calibration

Product development is very fast because all data and test reports for each product are managed automatically, and regular data analysis and product/process improvement are made.

TemcoLine's pride-fully automated contact areas like JIG PIN regarding calibration errors are maintained in the best conditions through ultrasonic wash and regular replacement.

# T50 SERIES High-quality functions, High precise control and Modbus communication

T50 Series is high-end PID Controller with high-quality convenient functions, supporting most protocols used in Korea. It offers excellent control stability through SG-PID controlling and advanced digital filtering technology.



Universal input/output (Input 24 types /Output 4 types)



New concept Auto-sampling(50~250ms) control



20 alarm options and 3 event output option  
Output port selectable



RS485 communication with fully independent isolation structure (PC/TL-link, Modbus-ASCII/RTU and other 2 options)



Control type can be set (Heating, Cooling, Heating and cooling control)



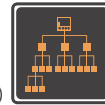
Super 2 degree of freedom PID algorithm



Fast mode, 3-Zone PID, Ramp function, Quick-AT, Easy-Menu



Current monitor (offset, hold function)  
Heater burnout alarm(HBA)  
Heater usage time (heater life prediction)



Support SYNC communication and possible to use Synchronous communication up to 250 by adjusting Sync-Master/Slave



Providing Remote supervisory control software and Data viewer which offer more powerful temperature recording and integrated management function



T50 series' remote supervisory control software provides the graphical temperature recording and it's very useful to monitor the examination of the precision control machine and the slight variations of the temperature, and also helpful to analysis output data in laboratory.

## General Specification

Power Supply	Rating 100~240V AC 50~60Hz (voltage operating range: 85~265V AC) ※ Option: Rating 24V AC or DC (operating voltage range 20~28V DC)	
Power Consumption	5VA (Max.)	
Input Type	TC: K, J, T, E, R, B, S, L, N, U, C(W5), D(W3) Platinum RTD: KPt100(KS), JPt100(JIS), Pt100(DIN) Current input (A): 4~20mA DC Voltage input (V): 1~5V DC, -10~20mV DC, 0~100mV DC	
Display Accuracy	±0.3% of FS + 1 Digit	
Input Impedance	Current input(250Ω), Voltage input(includingTC) ≥ 1MΩ min. (RTD line resistance: ≤ 10Ω, when 3-line resistance are the same)	
Input Sampling Period	50~250ms (variable according to SG-PID algorithm)	
Control Output	Relay	1c 250V AC, 3A(resistance load) electric lifespan ≥ 100,000 min. (time proportional PID output or ON/OFF output)
	Voltage (S.S,R)	DC15V 25mA (Built-in short protection circuit) Voltage pulse (time proportional PID output)
	Current (S.C,R)	4~20mA DC, load impedance ≤ 600Ω (continuous PID output)
Control Method	Super 2 degree-of-freedom PID (SG-PID algorithm), Fast, Auto-Tuning	
Multi SV Input (D.I)	ON: ≤ 1KΩ, OFF: ≥ 100KΩ (external control SV1, 2, 3)	
Retransmission Output	4~20mA DC, load impedance ≤ 600Ω resolution 1/4,600 PV(process value), SV(set value), MV(manipulated variable [%]), SPS(sensor module power supply)	
Alarm Output	ALARM 1,2 HBA common (C.T)	1a 250V AC 3A (Resistive load) HBA : 0.1 ~ 38.0 A AC (Resolution 0.1A)
Communication Output	2 wires RS485 totally independent isolation structure Max. speed : 19,200bps/ Max. connect no. 99 devices (32 devices recommended) Support protocol : PC-Link, TL-Link, Modbus-ASCII, Modbus-RTU	
Ambient Temperature and Humidity	-10~50℃/ relative humidity 25~85% RH (but with neither condensation nor freezing)	
Weight (B/K, Accessories included)	■ T52, T53, T57: 230g    ■ T54: 140g    ■ T59: 320g    *if options are added + 30g	

# T52 / T53

48x96x77 mm / 96x48x77 mm  
T52, T53 - C00 / C10

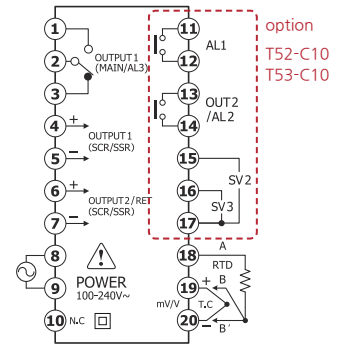


## Optional Function

- Basic : 1 relay output
- 2 SSR & SCR output
- 2 alarm output
- retransmission output(4~20mA)

- Standard C00 : multi SV input(DI)
- Option C10 : RS-485 communication
- heater burnout alarm(HBA)

## Terminal Configuration

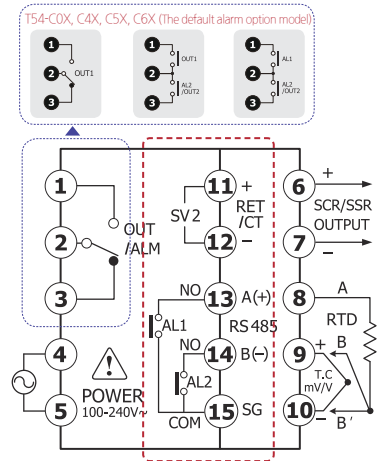


# T54

48x48x77 mm  
T54 - C00 / C10 / C20  
C30 / C40 / C50  
C60 / C70



- Basic C00 : 1 relay output
- 1 SSR & SCR output
- 1 alarm output
- Option C10 : 1 retransmission output
- 2 alarm output
- C20 : heater burnout alarm(HBA)
- 2 alarm output
- C30 : multi SV input
- 2 alarm output
- C40 : 1 retransmission output
- RS-485 communication
- C50 : heater burnout alarm(HBA)
- RS-485 communication
- C60 : multi SV input
- RS-485 communication
- C70 : RS-485 communication
- 2 alarm output

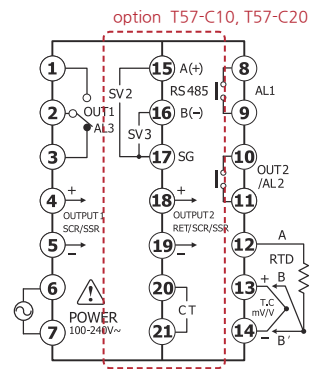


# T57

72x72x77 mm  
T57 - C00 / C10 / C20



- Basic C00 : 1 relay output
- 1 SSR & SCR output
- 2 alarm output
- Option C10 : RS-485 communication
- retransmission output(4~20mA)
- heater burnout alarm(HBA)
- C20 : multi SV input(DI)
- retransmission output(4~20mA)
- heater burnout alarm(HBA)

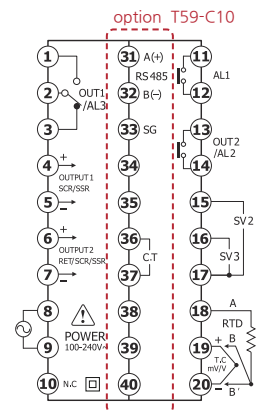


# T59

96x96x77 mm  
T59 - C00 / C10



- Basic C00 : 1 relay output
- 1 SSR & SCR output
- 2 alarm output
- retransmission output(4~20mA)
- multi SV input(DI)
- Option C10 : RS-485 communication
- heater burnout alarm(HBA)



## T30 SERIES Easy control, High precise control and High speed responsibility

T30 Series is economical and basic PID Controller with high-precision control, various convenient functions and very high-response speed.



Universal input/output  
(Input 24 types /  
Output 4 types)



New concept Auto-sampling(50~250ms) control



20 alarm options and  
3 event output option



Control loop break alarm  
(LBA)



Super 2 degree of freedom  
PID algorithm



2-Zone PID, External input SV1  
and SV2, Input digital filtering  
function



Timer(6 type)  
External digital input (DI)  
(Run / Stop)



Retransmission output

### General Specification

<b>Power Supply</b>	Rating 100~240V AC 50~60Hz (voltage operating range: 85~265V AC) ※ Option: Rating 24V AC or DC (operating voltage range 20~28V DC)	
<b>Power Consumption</b>	5VA (Max.)	
<b>Input Type</b>	TC: K, J, T, E, R, B, S, L, N, U, C(W5), D(W3) Platinum RTD: KPt100(KS), JPt100(JIS), Pt100(DIN) Current input (A): 4~20mA DC Voltage input (V): 1~5V DC, -10~20mV DC, 0~100mV DC	
<b>Display Accuracy</b>	±0.3% of FS + 1 Digit	
<b>Input Impedance</b>	Current input(250Ω), Voltage input(including TC) ≥ 1MΩ min. (RTD line resistance: ≤ 10Ω, when 3-line resistance are the same)	
<b>Input Sampling Period</b>	50~250ms (variable according to SG-PID algorithm)	
<b>Control Output</b>	<b>Relay</b>	1c 250V AC, 3A(resistance load) electric lifespan ≥ 100,000 min. (time proportional PID output or ON/OFF output)
	<b>Voltage (S,S,R)</b>	DC15V 25mA (Built-in short protection circuit) Voltage pulse (time proportional PID output)
	<b>Current (S,C,R)</b>	4~20mA DC, load impedance ≤ 600Ω (continuous PID output)
<b>Control Method</b>	Super 2 degree-of-freedom PID (SG-PID algorithm), Auto-Tuning	
<b>Multi SV Input (D.I)</b>	ON: ≤ 1KΩ, OFF: ≥ 100KΩ (external control SV1, 2)	
<b>Retransmission Output</b>	4~20mA DC, load impedance ≤ 600Ω resolution 1/4,600 PV(process value), SV(set value), MV(manipulated variable [%]), SPS(sensor module power supply)	
<b>Alarm Output</b>	<b>Alarm 1, 2 (LBA common)</b>	1a 250V AC 3A (Resistive load) 20 types of independent event output & Control loop break alarm
<b>Ambient Temperature and Humidity</b> -10~50℃/ relative humidity 25~85% RH (but with neither condensation nor freezing)		
<b>Weight (B/K, Accessories included)</b> ■ T32, T33, T37: 230g ■ T34: 140g ■ T39: 320g *if options are added + 30g		

# T32 / T33

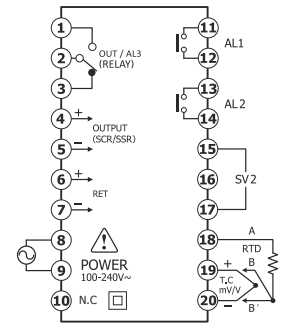
48x96x77 mm / 96x48x77 mm



## Optional Function

- Basic S00 : 1 relay output  
 1 SSR & SCR output  
 2 alarm output  
 retransmission output(4~20mA)  
 multi SV input(DI)

## Terminal Configuration



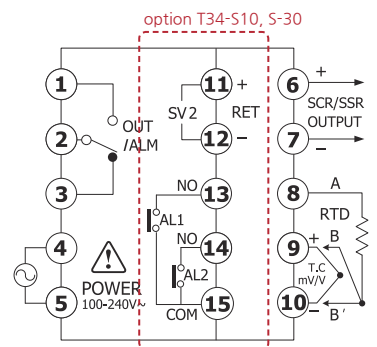
# T34

48x48x77 mm  
 T34 - S00 / S10 / S30



- Basic S00 : 1 relay output  
 1 SSR & SCR output

- Option S10 : 1 retransmission output  
 2 alarm output  
 S30 : multi SV input  
 2 alarm output



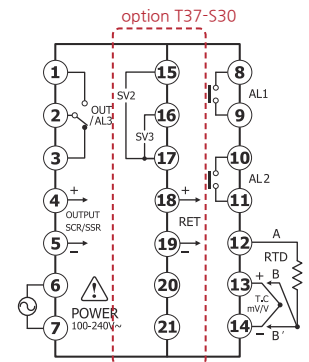
# T37

72x72x77 mm  
 T37 - S00 / S30



- Basic S00 : 1 relay output  
 1 SSR & SCR output  
 2 alarm output

- Option S30 : multi SV input(DI)  
 retransmission output(4~20mA)

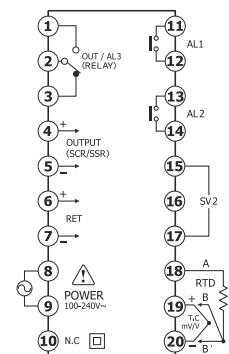


# T39

96x96x77 mm  
 T39 - S00



- Basic S00 : 1 relay output  
 1 SSR & SCR output  
 2 alarm output  
 retransmission output(4~20mA)  
 multi SV input(DI)



# T30 SERIES - TIMER

ALARM 2 of the T30 series supports powerful digital timer function.

## 1. Output operation mode (ALARM 2)

Normal : ON-Delay

- T1 : ON-Time, Auto Run (one shot)
- T2 : ON-Time, Manual Run (one shot)
- T3 : ON-Time, Manual Run (one shot) : without temperature
- T4 : Flicker (ON-Time setting from front display)
- T5 : Flicker (OFF-Time setting from front display)

Except the time set from the front, it is set in the internal menu.

## 2. 2 time units

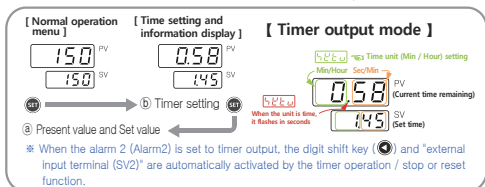
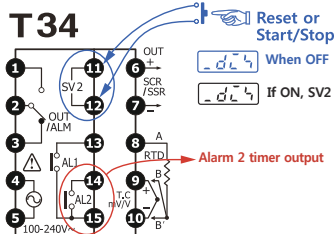
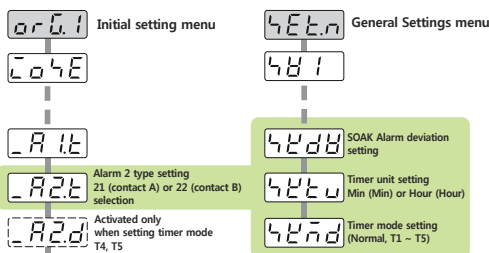
## 3. External digital input (DI)



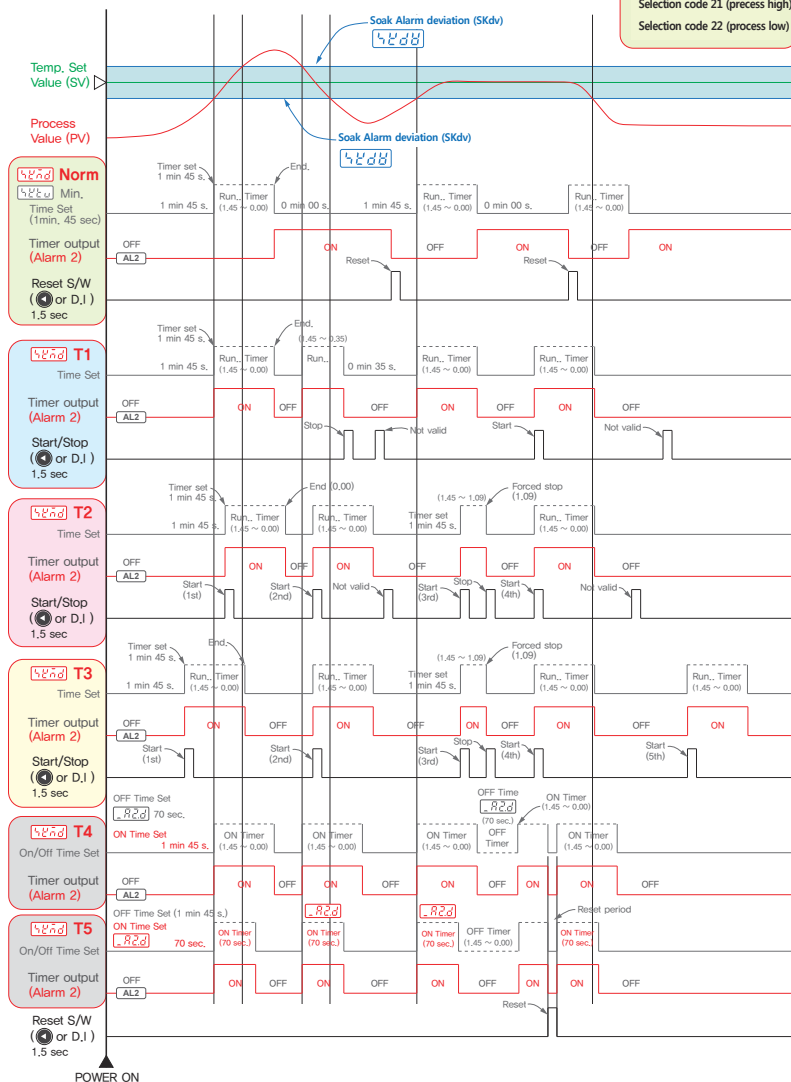
## Timer (normal, T1~5) Output Operation Timing Chart

### < SOAK alarm and timer output >

< Alarm type setting >      < Timer mode, unit, deviation setting >

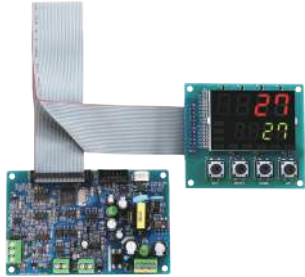


◆ Alarm setting   822    
Selection code 21 (process high)  
Selection code 22 (process low)



# N50 SERIES Board Type PID Controller

N50 Series is an integrated board type product based on T50 Series. The series has high performance to configure various systems/applications at economical cost. With its powerful communication function and excellent control characteristics, N50 is exclusively used for semiconductor test equipment of global companies.



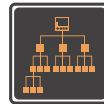
Universal input/output  
(Input 24 types /Output 4 types)



New concept Auto-sampling(50~250ms) control



RS485 communication with fully independent isolation structure (PC/TL-link, Modbus-ASCII/RTU and other 2 options)



Support SYNC communication and possible to use Synchronous communication up to 250 by adjusting Sync-Master/Slave



Providing Remote supervisory control software and Data viewer which offer more powerful temperature recording and integrated management function



Super 2 degree of freedom PID algorithm



Fast mode, 3-Zone PID, Ramp function, Quick-AT, Easy-Menu



20 alarm options and 3 event output option  
Output port selectable

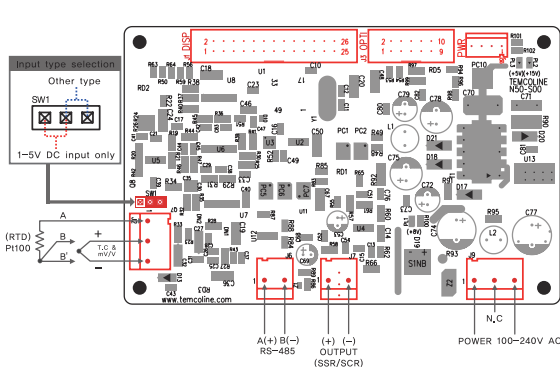


Current monitor (offset, hold function)  
Heater burnout alarm(HBA)  
Heater usage time (heater life prediction)

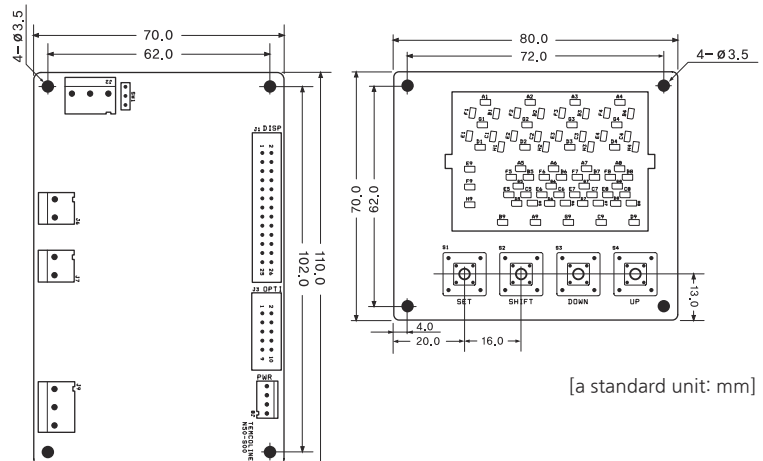
option

## General Specification

Power Supply	Rating 100~240V AC 50~60Hz (voltage operating range: 85~265V AC) ※ Option: Rating 24V AC or DC (operating voltage range 20~28V DC)
Power Consumption	5VA (Max.)
Input Type	TC: K, J, T, E, R, B, S, L, N, U, C(W5), D(W3) Platinum RTD: KPt100(KS), JPt100(JIS), Pt100(DIN) Current input (A): 4~20mA DC Voltage input (V): 1~5V DC, -10~20mV DC, 0~100mV DC
Display Accuracy	±0.3% of FS + 1 Digit
Input Impedance/Input	Current input(250 Ω), Voltage input(including TC) ≥ 1MΩ min. (RTD line resistance: ≤ 10Ω, when 3-line resistance are the same)
Sampling Period	50~250ms (variable according to SG-PID algorithm)
Control Output	Voltage (S.S.R) DC15V 25mA (Built-in short protection circuit) Voltage pulse (time proportional PID output)
	Current (S.C.R) 4~20mA DC, load impedance ≤ 600Ω (continuous PID output)
Control Method	Super 2 degree-of-freedom PID (SG-PID algorithm), Fast, Auto-Tuning
Communication Output	2 wires RS485 totally independent isolation structure Max. speed : 19,200bps / Max. connect no. 99 devices (32 devices recommended) Support protocol : PC-Link, TL-Link, Modbus-ASCII, Modbus-RTU
Ambient Temperature and Humidity	-10~50°C / relative humidity 25~85% RH (but with neither condensation nor freezing)
Weight (B/K, Accessories included)	Main Board: 66g / Display Board: 35g / Connectable Cable: 24g



Terminal Configuration



[a standard unit: mm]

## 1. Check point before using

### 1) Initial Value

**INPUT : K-Type(sel.code 1) OUTPUT : SSR mode(sel.code 1)**

In the case of standard model T34-S00 only, when SSR(1) and SCR(2) are chosen as the output mode, Alarm1 output will be in the main relay.

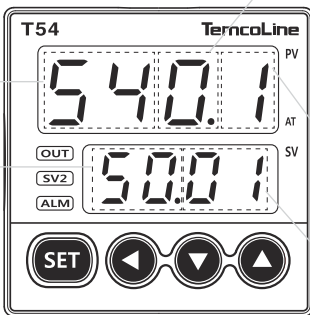
### 2) 7 Segment display indications

A	B	C	D	E	F	G	H	I	J	K	L	M	N	O	P	Q	R	S	T	U	V	W	X	Y	Z
ā	ā	ā	ā	ā	ā	ā	ā	ā	ā	ā	ā	ā	ā	ā	ā	ā	ā	ā	ā	ā	ā	ā	ā	ā	ā

### 3) Initial display on power supply(ex. model T54)

**Model name**

**Firmware version**



**Option**

- 0 : NONE
- 1 : RET, ALARM1, 2
- 2 : HBA(CT), ALARM1, 2
- 3 : DI(SV1, 2), ALARM1, 2
- 4 : RET, RS-485
- 5 : HBA(CT), RS-485
- 6 : DI(SV1, 2), RS-485
- 7 : RS-485, ALARM1, 2

**Output type**

- 0 : RELAY ON/OFF CONTROL
- 1 : SSR (VOLT-PULSE) PID CONTROL
- 2 : SCR (4~20mA) PID CONTROL
- 3 : RELAY PID CONTROL

**Input type**

- 01 : K-Type (-200~1370 °C)
- 02 : K-Type (-199.9~999.9 °C)
- :
- 33 : mV DC (0~100mV)

## 2. Initial installation and minimum operation procedure

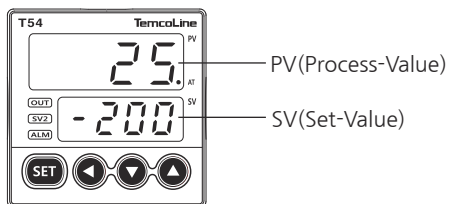
### 1) Check the external wiring diagram and specification (power supply & terminal arrangement)

### 2) Check input and output type

T50 and T30 Series are universal input and output. It must be chosen the correct input and output.

At first, should be set input type setting and then will be change others. Because if you change the input type, all setting value were reset.

#### ① Input type selection



**T50 SERIES**

Press and holding more than 3 sec. (SET) → dL4P → (SET) Press shortly → 0.ctr → (SET) → 9Ln → (SET) → LnP → (SET) → 1

or (SET) → (SET) Press shortly → LnP → (SET) → 1

← or →, ▲ set a desired value press (SET) store value.

**T30 SERIES**

Press and hold simultaneously more than 3 sec. (SET) + ← → (SET) Press shortly → LnP → (SET) → 1

Input type selection code table				
INPUT TYPE	SETTING CODE	TEMPERATURE RANGE	ACCURACY	REMARK
Thermo couple (T.C)	K	1	-200 ~ 1370	±0.3% of F.S +1Digit * F.S is max. value to min.value of each range. * Digit is minimum of display.
		2	-199.9 ~ 999.9	
	J	15	-200 ~ 1000	
		3	-199.9 ~ 999.9	
	E	16	-200 ~ 1000	
		4	-199.9 ~ 999.9	
	T	5	-199.9 ~ 400.0	
	R	6	0 ~ 1700	
	B	7	400 ~ 1800	
	S	8	0 ~ 1700	
	L	17	-200 ~ 900	
	N	9	-199.9 ~ 900.0	
	U	11	-199.9 ~ 400.0	
RTD	JP1100Ω (JIS, KS)	20	-199.9 ~ 500.0	
		22	-200 ~ 500	
	P1100Ω (DIN, IEC)	21	-199.9 ~ 640.0	
		23	-200 ~ 640	
Voltage (V DC/mV DC)	0~100 mV DC	33	0 ~ 100 mV DC	
	-10~20 mV DC	32	-10 ~ 20 mV DC	
	1~5 V DC	30	1~5 V DC	
Current	4~20mA DC	30	When using current input, use the resistor 250Ω on input terminal.	

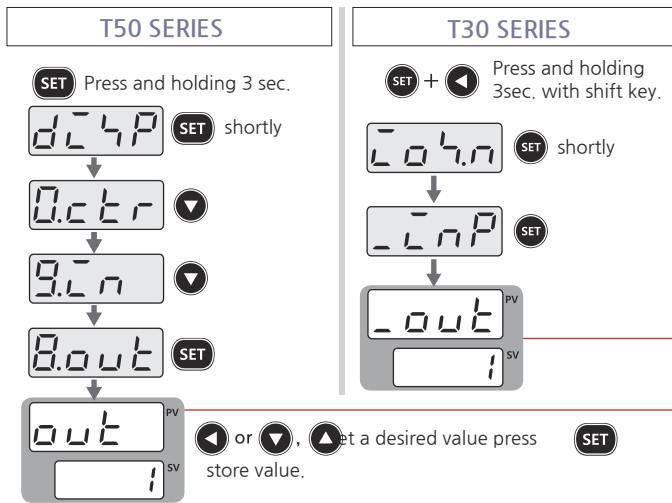
**※ How to change the interior switch when using 1~5V input**

① Remove plate or take out the main cover.

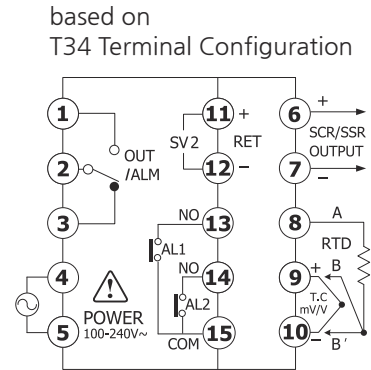
② Move and insert the jumper that pulled by tweezers.

③ Relocated jumper as above and attach plate or mounted cover.

## ② Output Setting



Output Set No.	Control Output	Output Terminal (T34)
0	RELAY ON/OFF CONTROL	①, ②, ③
1	SSR PID CONTROL	⑥, ⑦
2	SCR(4~20mA) PID CONTROL	⑥, ⑦
3	RELAY PID CONTROL	①, ②, ③

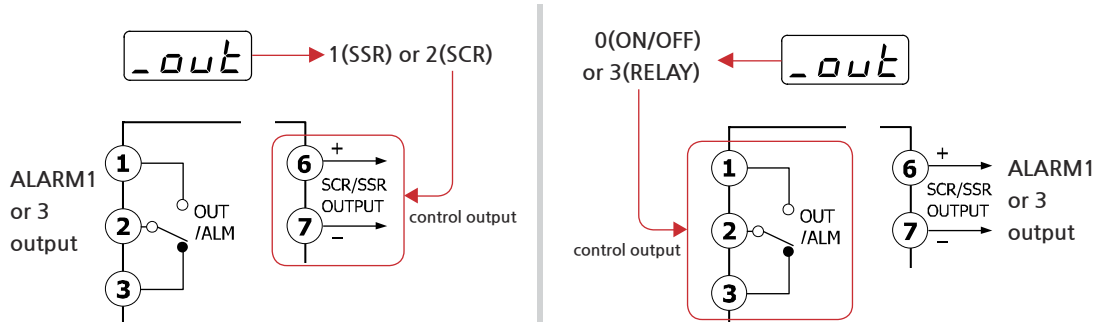


If press Set key (SET) more than 3sec. in the entering setting menu, it will be return to operating menu.  
Also AT(Auto-Tuning) has been completed, input/output mode will limited.  
It is ensure safety and protect from user miscontrol.  
If you need resetting, please refer to the user's manual.

### Output Set Number

- 1** : SSR output of PID control(Voltage Pulse) **[output set number: 1]**  
This is the General Setting and Initial Value.
- 2** : SCR output of PID control(4~20mA current output) **[output set number: 2]**  
This setting is used mainly with thyristor power regulator(TPR) modules and is capable of precision control.
- 3** : Relay output of PID control **[output set number: 3]**  
This is most cost-efficient method of implementing PID control and is used mainly with magnetic switches(electric switches).  
However, it may wear the contact point, and is difficult to use in places that require fast response.
- 0** : Relay output of ON/OFF control **[output set number: 0]**  
This is simple on/off control mainly used to control cooling devices.(Do not use Heating control.)

### Alarm output of T34(48×48) standard model(S00)



It is only for T34-S00!

With the standard model of T34(48×48) is required caution when using it alarm output. When control output is being used as a relay, the alarm output will be SSR output (voltage pulse).

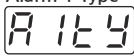
In this case take SSR or alarm option (S10, S30) enabled models.

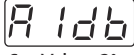
### ③ Alarm Type and Selection code

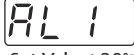
T50/T30 Series have three independent alarm outputs, and are able to use the event mode variously.


#### < Example of Alarm 1 output Setting >

**T50 SERIES**

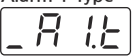
Alarm 1 Type  
  
 Set Value: 03

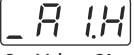
Alarm 1 Dead band  
  
 Set Value: 2°C

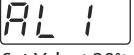
Alarm 1 Set Value  
  
 Set Value: 20°C

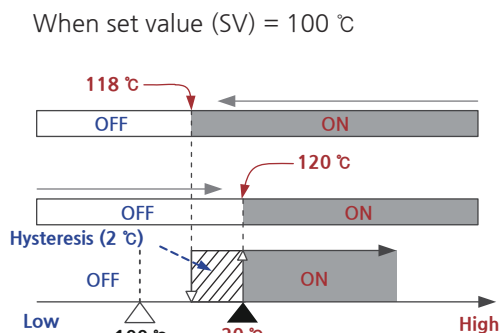
Alarm 1 Output port  
  
 Set Value: AL 1

**T30 SERIES**

Alarm 1 Type  
  
 Set Value: 03

Alarm 1 Hysteresis  
  
 Set Value: 2°C

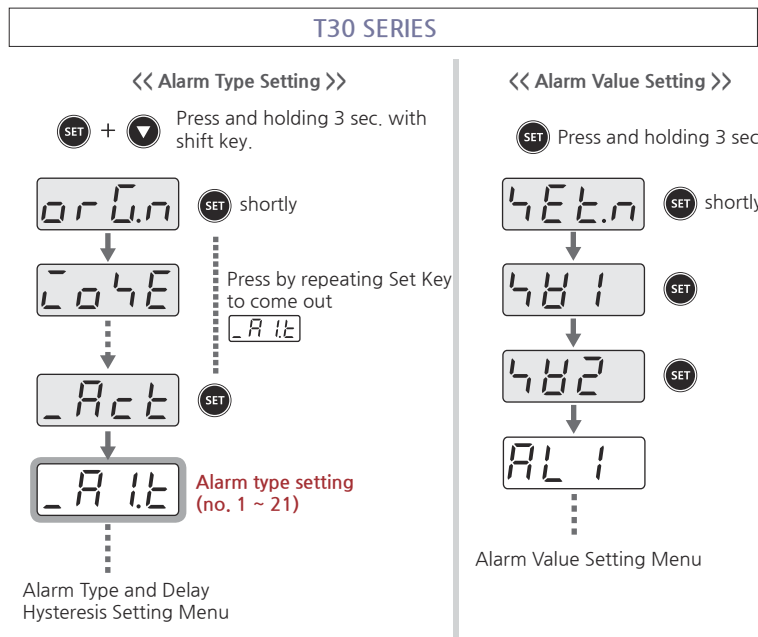
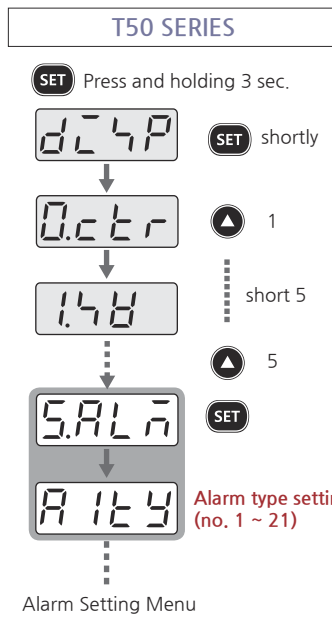
Alarm 1 Set Value  
  
 Set Value: 20°C



Alarm output type and Selection code		
Code no.	Alarm type	Alarm output operation
01	Absolute value upper-limit	When temperature is falling: OFF to ON
09	Process low	When temperature is rising: OFF to ON
11	with hold function	Temperature graph showing hysteresis
19	with hold function (Inverted)	Temperature graph showing hysteresis
02	Absolute value lower-limit	When temperature is falling: ON to OFF
10	Process low	When temperature is rising: ON to OFF
12	with hold function	Temperature graph showing hysteresis
20	with hold function (Inverted)	Temperature graph showing hysteresis
03	Upper-limit deviation	< Negative temp. value setting >: OFF to ON when falling; < Positive temp. value setting >: OFF to ON when rising
05	Process low	< Negative temp. value setting >: OFF to ON when falling; < Positive temp. value setting >: OFF to ON when rising
13	with hold function	Temperature graph showing hysteresis
15	with hold function (Inverted)	Temperature graph showing hysteresis
04	Lower-limit deviation	< Negative temp. value setting >: ON to OFF when falling; < Positive temp. value setting >: ON to OFF when rising
06	Process low	< Negative temp. value setting >: ON to OFF when falling; < Positive temp. value setting >: ON to OFF when rising
14	with hold function	Temperature graph showing hysteresis
16	with hold function (Inverted)	Temperature graph showing hysteresis
07	Upper & Lower-limit deviation	When temperature is falling: ON to OFF to ON; When temperature is rising: ON to OFF to ON
17	Upper & Lower-limit deviation with hold	Temperature graph showing hysteresis
08	Upper & Lower-limit deviation in range	When temperature is falling: OFF to ON to OFF; When temperature is rising: OFF to ON to OFF
18	Upper & Lower-limit deviation in range with hold	Temperature graph showing hysteresis
21	Heater break alarm (HBA)	Refer to HBA (ALARM1 only)
	Control Loop break alarm	LBA operation when heater break alarm (HBA) is not used. (ALARM1 only)

T30(TIMER) ALARM OUTPUT TYPE AND SELECTION CODE		
CODE NO.	ALARN TYPE	ALARM OUTPUT OPERATION
21	ALARM 1	Loop break alarm (LBA) Refer to Loop break alarm (LBA)! (ALARM1 only)
	ALARM 3	Inverter operation / stop output alarm Page 25, 1) Refer to inverter operation stop controll! (ALARM 3 only)
22	ALARM 2	[Alarm No. 2 code 21] Supports five kinds of SOAK alarm and timer output(Process high) (Setting mode T1 to T5)
		[Alarm No. 2 code 22] SOAK Alarm and Timer Output (Process low) refer to ※ Page 33, "14. SOAK alarm and timer output mode"

### < Alarm (AL1, AL2) Group Setting >

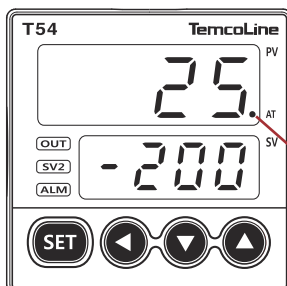


※ According to a set input type and function change a order of setting menu.

#### ④ Auto Tuning

PID Controller works normally only it that was tuned P,I,D value before to use.

Auto-tuning is function for the best performance by tuned itself automatically accroding to full load operating condition and sataus.



- ① Set to need a Set Value(SV).
- ② Start Auto-Tuning(AT).
- ③ Hold on when turn automatically off a AT indicator lamp.

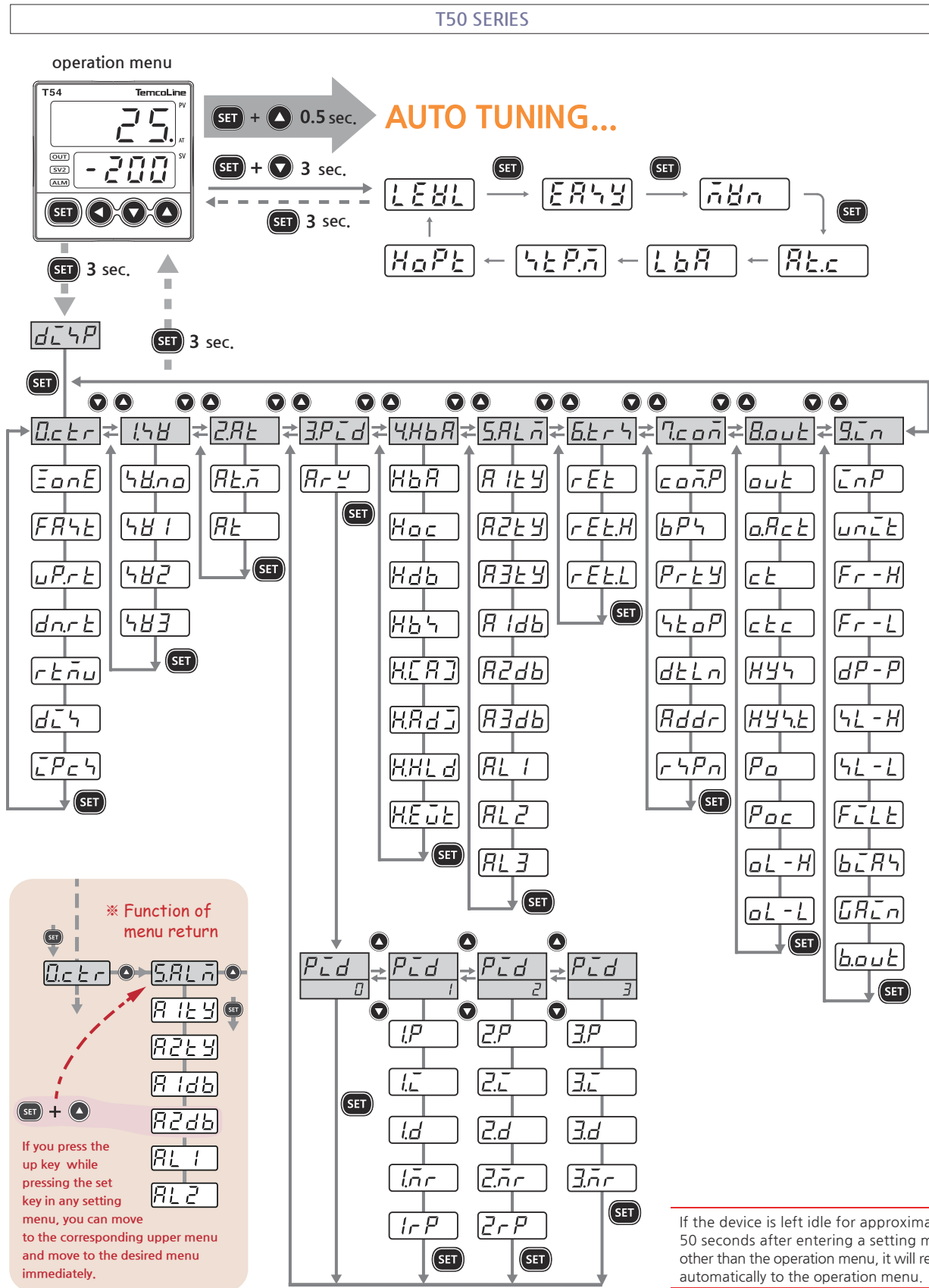
AT indicator lamp

AT operation start : SET + ▲ 0.5 second

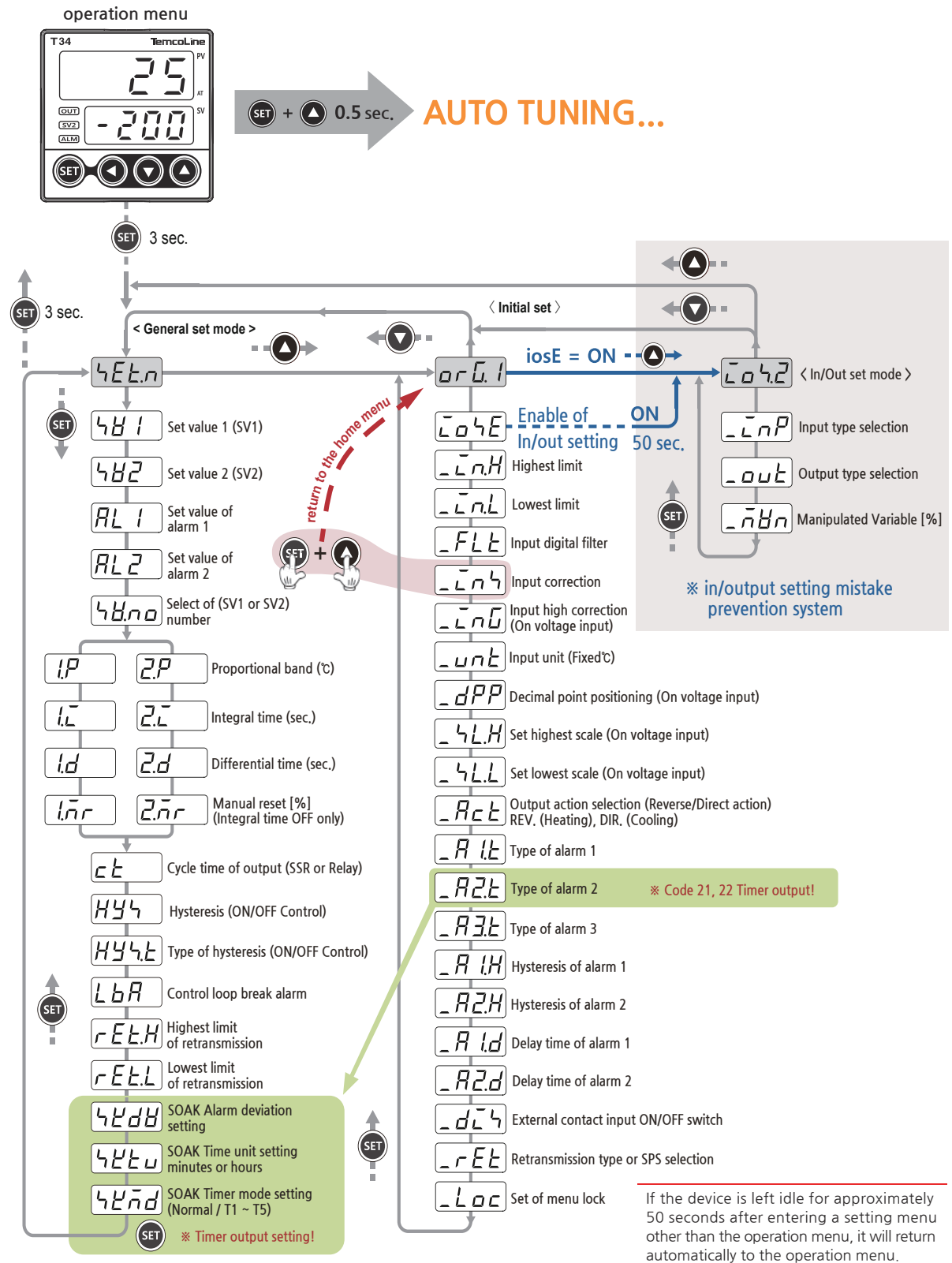
AT stop by performe : SET + ▲ 0.5 second

When auto-tuning begins, the "auto-tuning indicator lamp" will blinking every 0.5 second and will turn off upon completion of the tuning process. If you change a set value(SV) in auto-tuning, proceed the tuning before to work on auto-tuning.

3. Flow Chart (Parameter structure)



The full menu diagram above shows all control and setting menus on the T50 series/ T30 Series, but during actual operations the menus that are the most relevant to the situation according to the options and the operation mode, providing a simpler user interface while retaining functionality.



The above is a brief explanation of the operation. For more information, please refer to user's manual that is included in product.

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